

≡ **Note** If the y_{p_i} are particular solutions of (12) for $i = 1, 2, \dots, k$, then the linear combination

$$y_p = c_1 y_{p_1} + c_2 y_{p_2} + \cdots + c_k y_{p_k}$$

where the c_i are constants, is also a particular solution of (14) when the right-hand member of the equation is the linear combination

$$c_1 g_1(x) + c_2 g_2(x) + \cdots + c_k g_k(x).$$

Before we actually start solving homogeneous and nonhomogeneous linear differential equations, we need one additional bit of theory, which is presented in the next section.

REMARKS

This remark is a continuation of the brief discussion of dynamical systems given at the end of Section 1.3.

A dynamical system whose rule or mathematical model is a linear n th-order differential equation

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_1(t)y' + a_0(t)y = g(t)$$

is said to be an n th-order **linear system**. The n time-dependent functions $y(t)$, $y'(t)$, \dots , $y^{(n-1)}(t)$ are the **state variables** of the system. Recall that their values at some time t give the **state of the system**. The function g is variously called the **input function**, **forcing function**, or **excitation function**. A solution $y(t)$ of the differential equation is said to be the **output** or **response of the system**. Under the conditions stated in Theorem 4.1.1, the output or response $y(t)$ is uniquely determined by the input and the state of the system prescribed at a time t_0 —that is, by the initial conditions $y(t_0)$, $y'(t_0)$, \dots , $y^{(n-1)}(t_0)$.

For a dynamical system to be a linear system, it is necessary that the superposition principle (Theorem 4.1.7) holds in the system; that is, the response of the system to a superposition of inputs is a superposition of outputs. We have already examined some simple linear systems in Section 3.1 (linear first-order equations); in Section 5.1 we examine linear systems in which the mathematical models are second-order differential equations.

EXERCISES 4.1

Answers to selected odd-numbered problems begin on page ANS-4.

4.1.1 INITIAL-VALUE AND BOUNDARY-VALUE PROBLEMS

In Problems 1–4 the given family of functions is the general solution of the differential equation on the indicated interval. Find a member of the family that is a solution of the initial-value problem.

- $y = c_1 e^x + c_2 e^{-x}$, $(-\infty, \infty)$;
 $y'' - y = 0$, $y(0) = 0$, $y'(0) = 1$
- $y = c_1 e^{4x} + c_2 e^{-x}$, $(-\infty, \infty)$;
 $y'' - 3y' - 4y = 0$, $y(0) = 1$, $y'(0) = 2$
- $y = c_1 x + c_2 x \ln x$, $(0, \infty)$;
 $x^2 y'' - xy' + y = 0$, $y(1) = 3$, $y'(1) = -1$
- $y = c_1 + c_2 \cos x + c_3 \sin x$, $(-\infty, \infty)$;
 $y''' + y' = 0$, $y(\pi) = 0$, $y'(\pi) = 2$, $y''(\pi) = -1$

- Given that $y = c_1 + c_2 x^2$ is a two-parameter family of solutions of $xy'' - y' = 0$ on the interval $(-\infty, \infty)$, show that constants c_1 and c_2 cannot be found so that a member of the family satisfies the initial conditions $y(0) = 0$, $y'(0) = 1$. Explain why this does not violate Theorem 4.1.1.
- Find two members of the family of solutions in Problem 5 that satisfy the initial conditions $y(0) = 0$, $y'(0) = 0$.
- Given that $x(t) = c_1 \cos \omega t + c_2 \sin \omega t$ is the general solution of $x'' + \omega^2 x = 0$ on the interval $(-\infty, \infty)$, show that a solution satisfying the initial conditions $x(0) = x_0$, $x'(0) = x_1$ is given by

$$x(t) = x_0 \cos \omega t + \frac{x_1}{\omega} \sin \omega t.$$

8. Use the general solution of $x'' + \omega^2 x = 0$ given in Problem 7 to show that a solution satisfying the initial conditions $x(t_0) = x_0, x'(t_0) = x_1$ is the solution given in Problem 7 shifted by an amount t_0 :

$$x(t) = x_0 \cos \omega(t - t_0) + \frac{x_1}{\omega} \sin \omega(t - t_0).$$

In Problems 9 and 10 find an interval centered about $x = 0$ for which the given initial-value problem has a unique solution.

9. $(x - 2)y'' + 3y = x, \quad y(0) = 0, \quad y'(0) = 1$
 10. $y'' + (\tan x)y = e^x, \quad y(0) = 1, \quad y'(0) = 0$
 11. (a) Use the family in Problem 1 to find a solution of $y'' - y = 0$ that satisfies the boundary conditions $y(0) = 0, y(1) = 1$.
 (b) The DE in part (a) has the alternative general solution $y = c_3 \cosh x + c_4 \sinh x$ on $(-\infty, \infty)$. Use this family to find a solution that satisfies the boundary conditions in part (a).
 (c) Show that the solutions in parts (a) and (b) are equivalent.
 12. Use the family in Problem 5 to find a solution of $xy'' - y' = 0$ that satisfies the boundary conditions $y(0) = 1, y'(1) = 6$.

In Problems 13 and 14 the given two-parameter family is a solution of the indicated differential equation on the interval $(-\infty, \infty)$. Determine whether a member of the family can be found that satisfies the boundary conditions

13. $y = c_1 e^x \cos x + c_2 e^x \sin x; \quad y'' - 2y' + 2y = 0$
 (a) $y(0) = 1, \quad y'(\pi) = 0$
 (b) $y(0) = 1, \quad y(\pi) = -1$
 (c) $y(0) = 1, \quad y(\pi/2) = 1$
 (d) $y(0) = 0, \quad y(\pi) = 0$
 14. $y = c_1 x^2 + c_2 x^4 + 3; \quad x^2 y'' - 5xy' + 8y = 24$
 (a) $y(-1) = 0, \quad y(1) = 4$
 (b) $y(0) = 1, \quad y(1) = 2$
 (c) $y(0) = 3, \quad y(1) = 0$
 (d) $y(1) = 3, \quad y(2) = 15$

4.1.2 HOMOGENEOUS EQUATIONS

In Problems 15–22 determine whether the given set of functions is linearly independent on the interval $(-\infty, \infty)$.

15. $f_1(x) = x, \quad f_2(x) = x^2, \quad f_3(x) = 4x - 3x^2$
 16. $f_1(x) = 0, \quad f_2(x) = x, \quad f_3(x) = e^x$
 17. $f_1(x) = 5, \quad f_2(x) = \cos^2 x, \quad f_3(x) = \sin^2 x$
 18. $f_1(x) = \cos 2x, \quad f_2(x) = 1, \quad f_3(x) = \cos^2 x$
 19. $f_1(x) = x, \quad f_2(x) = x - 1, \quad f_3(x) = x + 3$
 20. $f_1(x) = 2 + x, \quad f_2(x) = 2 + |x|$

21. $f_1(x) = 1 + x, \quad f_2(x) = x, \quad f_3(x) = x^2$
 22. $f_1(x) = e^x, \quad f_2(x) = e^{-x}, \quad f_3(x) = \sinh x$

In Problems 23–30 verify that the given functions form a fundamental set of solutions of the differential equation on the indicated interval. Form the general solution.

23. $y'' - y' - 12y = 0; \quad e^{-3x}, e^{4x}, (-\infty, \infty)$
 24. $y'' - 4y = 0; \quad \cosh 2x, \sinh 2x, (-\infty, \infty)$
 25. $y'' - 2y' + 5y = 0; \quad e^x \cos 2x, e^x \sin 2x, (-\infty, \infty)$
 26. $4y'' - 4y' + y = 0; \quad e^{x/2}, xe^{x/2}, (-\infty, \infty)$
 27. $x^2 y'' - 6xy' + 12y = 0; \quad x^3, x^4, (0, \infty)$
 28. $x^2 y'' + xy' + y = 0; \quad \cos(\ln x), \sin(\ln x), (0, \infty)$
 29. $x^3 y''' + 6x^2 y'' + 4xy' - 4y = 0; \quad x, x^{-2}, x^{-2} \ln x, (0, \infty)$
 30. $y^{(4)} + y'' = 0; \quad 1, x, \cos x, \sin x, (-\infty, \infty)$

4.1.3 NONHOMOGENEOUS EQUATIONS

In Problems 31–34 verify that the given two-parameter family of functions is the general solution of the nonhomogeneous differential equation on the indicated interval.

31. $y'' - 7y' + 10y = 24e^x;$
 $y = c_1 e^{2x} + c_2 e^{5x} + 6e^x, (-\infty, \infty)$
 32. $y'' + y = \sec x;$
 $y = c_1 \cos x + c_2 \sin x + x \sin x + (\cos x) \ln(\cos x),$
 $(-\pi/2, \pi/2)$
 33. $y'' - 4y' + 4y = 2e^{2x} + 4x - 12;$
 $y = c_1 e^{2x} + c_2 x e^{2x} + x^2 e^{2x} + x - 2, (-\infty, \infty)$
 34. $2x^2 y'' + 5xy' + y = x^2 - x;$
 $y = c_1 x^{-1/2} + c_2 x^{-1} + \frac{1}{15} x^2 - \frac{1}{6} x, (0, \infty)$
 35. (a) Verify that $y_{p_1} = 3e^{2x}$ and $y_{p_2} = x^2 + 3x$ are, respectively, particular solutions of
 $y'' - 6y' + 5y = -9e^{2x}$
 and $y'' - 6y' + 5y = 5x^2 + 3x - 16$.
 (b) Use part (a) to find particular solutions of
 $y'' - 6y' + 5y = 5x^2 + 3x - 16 - 9e^{2x}$
 and $y'' - 6y' + 5y = -10x^2 - 6x + 32 + e^{2x}$.
 36. (a) By inspection find a particular solution of
 $y'' + 2y = 10$.
 (b) By inspection find a particular solution of
 $y'' + 2y = -4x$.
 (c) Find a particular solution of $y'' + 2y = -4x + 10$.
 (d) Find a particular solution of $y'' + 2y = 8x + 5$.

Discussion Problems

37. Let $n = 1, 2, 3, \dots$. Discuss how the observations $D^n x^{n-1} = 0$ and $D^n x^n = n!$ can be used to find the general solutions of the given differential equations.
- (a) $y'' = 0$ (b) $y''' = 0$ (c) $y^{(4)} = 0$
 (d) $y'' = 2$ (e) $y''' = 6$ (f) $y^{(4)} = 24$
38. Suppose that $y_1 = e^x$ and $y_2 = e^{-x}$ are two solutions of a homogeneous linear differential equation. Explain why $y_3 = \cosh x$ and $y_4 = \sinh x$ are also solutions of the equation.
39. (a) Verify that $y_1 = x^3$ and $y_2 = |x|^3$ are linearly independent solutions of the differential equation $x^2 y'' - 4xy' + 6y = 0$ on the interval $(-\infty, \infty)$.
 (b) Show that $W(y_1, y_2) = 0$ for every real number x . Does this result violate Theorem 4.1.3? Explain.
 (c) Verify that $Y_1 = x^3$ and $Y_2 = x^2$ are also linearly independent solutions of the differential equation in part (a) on the interval $(-\infty, \infty)$.
 (d) Find a solution of the differential equation satisfying $y(0) = 0, y'(0) = 0$.
- (e) By the superposition principle, Theorem 4.1.2, both linear combinations $y = c_1 y_1 + c_2 y_2$ and $Y = c_1 Y_1 + c_2 Y_2$ are solutions of the differential equation. Discuss whether one, both, or neither of the linear combinations is a general solution of the differential equation on the interval $(-\infty, \infty)$.
40. Is the set of functions $f_1(x) = e^{x+2}, f_2(x) = e^{x-3}$ linearly dependent or linearly independent on $(-\infty, \infty)$? Discuss.
41. Suppose y_1, y_2, \dots, y_k are k linearly independent solutions on $(-\infty, \infty)$ of a homogeneous linear n th-order differential equation with constant coefficients. By Theorem 4.1.2 it follows that $y_{k+1} = 0$ is also a solution of the differential equation. Is the set of solutions $y_1, y_2, \dots, y_k, y_{k+1}$ linearly dependent or linearly independent on $(-\infty, \infty)$? Discuss.
42. Suppose that y_1, y_2, \dots, y_k are k nontrivial solutions of a homogeneous linear n th-order differential equation with constant coefficients and that $k = n + 1$. Is the set of solutions y_1, y_2, \dots, y_k linearly dependent or linearly independent on $(-\infty, \infty)$? Discuss.

4.2 REDUCTION OF ORDER

REVIEW MATERIAL

- Section 2.5 (using a substitution)
- Section 4.1

INTRODUCTION In the preceding section we saw that the general solution of a homogeneous linear second-order differential equation

$$a_2(x)y'' + a_1(x)y' + a_0(x)y = 0 \quad (1)$$

is a linear combination $y = c_1 y_1 + c_2 y_2$, where y_1 and y_2 are solutions that constitute a linearly independent set on some interval I . Beginning in the next section, we examine a method for determining these solutions when the coefficients of the differential equation in (1) are constants. This method, which is a straightforward exercise in algebra, breaks down in a few cases and yields only a single solution y_1 of the DE. It turns out that we can construct a second solution y_2 of a homogeneous equation (1) (even when the coefficients in (1) are variable) provided that we know a nontrivial solution y_1 of the DE. The basic idea described in this section is that *equation (1) can be reduced to a linear first-order DE by means of a substitution* involving the known solution y_1 . A second solution y_2 of (1) is apparent after this first-order differential equation is solved.

≡ Reduction of Order Suppose that y_1 denotes a nontrivial solution of (1) and that y_1 is defined on an interval I . We seek a second solution y_2 so that the set consisting of y_1 and y_2 is linearly independent on I . Recall from Section 4.1 that if y_1 and y_2 are linearly independent, then their quotient y_2/y_1 is nonconstant on I —that is, $y_2(x)/y_1(x) = u(x)$ or $y_2(x) = u(x)y_1(x)$. The function $u(x)$ can be found by substituting $y_2(x) = u(x)y_1(x)$ into the given differential equation. This method is called **reduction of order** because we must solve a linear first-order differential equation to find u .

